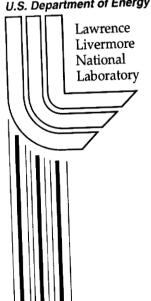
# Synchrotron Radiation **Computed Tomography** (SRCT) of Ruled Laser **Targets**

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## Synchrotron Radiation Computed Tomography (SRCT) of Ruled Laser Targets

### J.H. Kinney and David L. Haupt

Report on the suitability of synchrotron radiation for NIF characterization

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#### Introduction:

High spatial resolution tomography benefits from a high brightness source (photons/(mr² x source area)). A synchrotron radiation source provides extremely high continuous brightness with spectral characteristics suited to a wide variety of imaging needs. Therefore, during the initial testing of the new synchrotron radiation computed tomography (SRCT) system at Stanford Synchrotron Radiation Laboratory, it was suggested that we image a ruled target designed for NIF experiments. This is a detailed report of that imaging effort.

#### **Materials and Methods:**

A ruled, 1-mm diameter laser target of known construction was selected for imaging. The target was made of polyimid, with a brominated central insert. The surface had a three-dimensional sinusoidal pattern similar to that seen in an egg carton. The ruling was designed to have a 50  $\mu$ m period, and have a peak to valley height of 5  $\mu$ m.

The specimen was placed on the rotating stage of the SRCT system at beamline 10-2 at Stanford Synchrotron Radiation Laboratory,<sup>3</sup> and scanned in 0.25-degree rotational increments over  $180^{\circ}$ . A double crystal Si (220) monochromator was used to select an x-ray energy of 12 keV ( $\Delta E/E < 10^{-4}$ ).

X-rays were converted to visible light on a polished, single crystal cadmium tungstate scintillator. A thermoelectrically cooled CCD detector (Roper Scientific) acquired the visible light images. Image acquisition time was about 0.5 seconds per angular increment. Total imaging time was one hour (see discussion). A parallel reconstruction method using Fourier-filtered back projection generated a three-dimensional image of the specimen.

After reconstruction, a threshold was used to define the surface of the laser target. A cord was then generated from a reference plane above the sample to the surface at each (x,y) voxel in the slice plane. A least squares fit to a plane was performed on the (x,y) array of cord lengths, and the value of the plane was then subtracted from the cord length to correct for any misalignment of the specimen surface with respect to the reference plane. The corrected cord lengths formed a topographic map of the target surface.

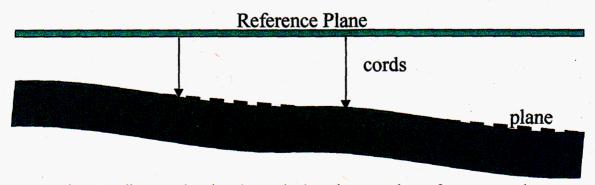


Figure 1: diagram showing the method used to map the surface topography.

#### **Results:**

As a result of the large contrast between the Br doped insert and the unbrominated pad, it has proved difficult to display a topographic image of the entire part in a single image. Therefore, we have chosen to display the insert separately. The sinusoidal pattern of the insert is clearly seen in Figure 2. The surface topography along the datum line is shown in the graph to the right. The period spacing averaged 56.3  $\mu$ m (+/- 5.1) and the peak-to-valley height averaged 5.7  $\mu$ m (+/- 0.9) (averaged from line intercepts perpendicular to the rule). These measurements are in line with the target specifications.<sup>4</sup>

An underlying sinusoidal pattern runs orthogonal to the strong rule pattern seen in Figure 2. This underlying pattern, measured along a trough shown by the datum line in Figure 3, has a sinusoidal nature with a mean peak-to-valley height of 5.4  $\mu$ m (+/- 1.3) (averaged from line intercepts perpendicular to the rule) and a period spacing of 97  $\mu$ m (+/- 1.4). These features were later confirmed visually.

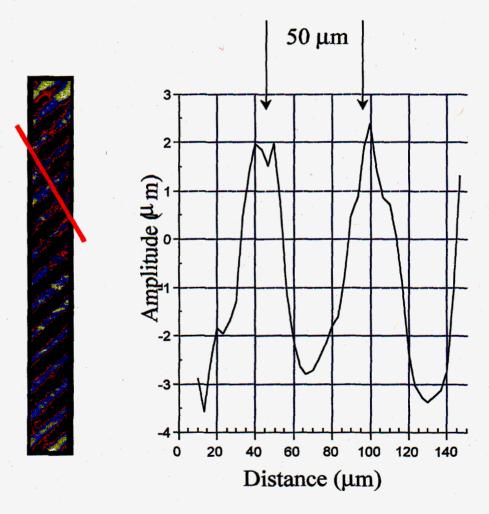


Figure 2: Left, a CT image of the insert surface. Right, a graphical presentation of the surface height along the datum line perpendicular to the upper rule pattern. The amplitude is with respect to the mean surface elevation.

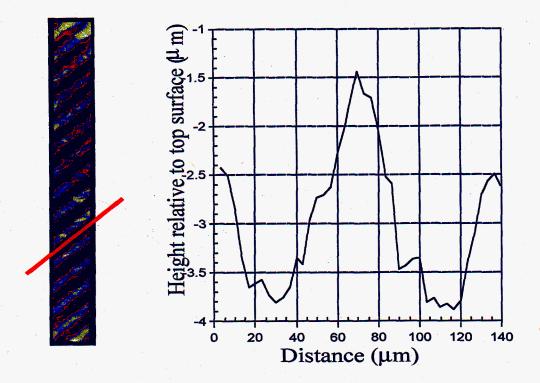


Figure 3: Left, the CT image of the insert. Right, a graphical representation of the surface height along the datum line parallel with the upper rule showing a wavelength twice that of the upper grating. Only a single peak is fully shown. The negative heights indicate that the surfaces lie below the mean surface elevation.

The unbrominated pad was more difficult to image, largely because of the extreme x-ray contrast of the insert. In future, an x-ray energy just below the Br edge would provide better contrast. A small section of the pad is shown in Figure 4, with a corresponding graph of the surface height along the datum line perpendicular to the rule. In contrast to the insert, the mean peak-to-valley height was 3.8  $\mu$ m (+/- 0.4). The period spacing also appeared to be different: 68.4  $\mu$ m (+/- 5.5). Topographic measurements in the trough were more difficult to make. Here, the period spacing was 81 mm (+/- 6) with a mean peak-to-valley height of 3.1  $\mu$ m (+/- 0.8).



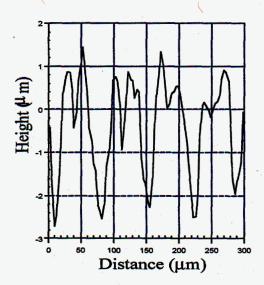


Figure 4: Left, a CT image of the unbrominated pad. Right, a graphical representation of the surface height along the datum line perpendicular to the upper rule.

#### Discussion:

SRCT was performed on the ruled laser target prior to our obtaining information of its composition. Compositional information would have allowed us to select a more optimum energy for imaging both the unbrominated pad and the brominated insert. Also, as this was a shakedown run, we did not have software control of the camera binning. All of the images were obtained with a binsize of two. Therefore, the resolving power of the camera was only half its designed maximum.

With traditional x-ray sources, exposure time is the limiting factor in data acquisition. With SRCT, however, exposure times are quite short (less than a second). Therefore, the time spent in reading the camera and moving the stages becomes the limiting factors in acquisition. In this study, 75% of the acquisition time was spent in activities other than exposing the image. The present version of the software was never optimized to take full advantage of the CCD camera; onboard memory was not used in image storage and partial frame readout was not utilized. Since this study, a new version of the data acquisition software has been produced that markedly speeds up hardware aspects of the data acquisition. We anticipate that camera readout and stage motion will no longer be a limiting factor in SRCT.

In spite of these limitations, SRCT shows itself to be capable of imaging surface relief to within a couple of microns without adopting any advanced imaging methods. With the new liquid nitrogen cooled monochromator that was recently put into service on beamline 10-2, the exposure time will be ten times shorter (50ms). Under optimized conditions, we anticipate that as many as 2-3 specimens could be 3-dimensionally imaged per hour.

Future designs call for the development of a dedicated imaging beamline at the Advanced Light Source at Lawrence Berkeley National Laboratory. The design allows for the insertion of an x-ray microscope if a user base can be established. In the microscope design, KB reflecting optics will be used as condensers, and a focusing Fresnel zone plate will be used as an objective lens. The spatial resolution of this system is conservatively estimated to be 0.1 µm with a field of view of 1 mm.

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